

### SAVITRIBAI PHULE PUNE UNIVERSITY

### **FACULTY OF ENGINEERING**

# SYLLABUS FOR M. E. ELECTRICAL (ELECTRIC VEHICLE TECHNOLOGY) (2017 COURSE)

### WITH EFFECT FROM YEAR 2017-18



# F.Y. M.E. (Electric Vehicle Technology) Semester -I

Subject		Teaching Scheme	Examination Scheme					
Code	Course		Paper			Oral/	Total	Credits
Code		Theory/Lab	ISE	ESE	TW	Presentation		
503501	Electric Vehicles	04	50	50	-	-	100	04
503502	Vehicle Dynamics	04	50	50	-	-	100	04
503503	Power Electronics Converters	04	50	50	-	-	100	04
503504	Research methodology	04	50	50	-	-	100	04
503505	Elective-I	05	50	50	-	-	100	05
503506	Lab Practice I- Electric vehicles Lab	04	-	-	50	50	100	04
	Total	25	250	250	50	50	600	25

	Elective I					
Code No.	Title					
503505A	Power Semiconductor Devices					
503505B	Automotive Electronics for EVs					
503505C	Control Systems and instrumentation in Automotive Systems					



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### **Semester -II**

Subject		Teaching Scheme Examination Scheme						
Code	Course	(T)	Paper			Oral/	Total	Credits
Code		Theory/Lab	ISE	ESE	TW	Presentation		
503507	Embedded System	4	50	50			100	4
503508	Battery Management System	4	50	50			100	4
503509	Charging Systems and Infrastructure	4	50	50			100	4
503510	Elective-II	5	50	50			100	5
503511	Lab Practice II Powertrain Lab	4			50	50	100	4
503512	Seminar-I	4			50	50	100	4
Total		25	250	250	50	50	600	25

Elective II				
Code No.	Title			
503510A	Energy Storage Systems and Management			
503510B	Electronic System Design			
503510C	Thermal Management of EV systems			



# S.Y. M.E. (Electric Vehicle Technology) Semester -III

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Subject		Teaching Scheme		<b>Examination Scheme</b>				
· ·	Course		Paj	per		Oral/	Total	Credits
Code		Theory/Lab	ISE	ESE	TW	Presentation		
603501	Advanced Battery Technology for Electrical Vehicles	04	50	50			100	04
603502	Advanced Electrical Machines	04	50	50			100	04
603503	Elective-III	05	50	50			100	05
603504	Seminar-II	04			50	50	100	04
603505	Project Stage -I	08			50	50	100	08
	Total	25	150				500	25

Elective III				
Code No.	Title			
603503A	Automotive Testing and Certification			
603503B	Automotive Embedded Systems and Communication Protocol			
603503C	Modeling and Simulation of EVs			

### **Semester -IV**

Subject		Teaching Scheme		Exa	mination	Scheme			
	Course		Paper Oral/			Total	Credits		
Code		Theory/Lab	ISE	ESE	TW	Presentation			
603506	Seminar-III	05			50	50	100	05	
603507	Project Stage -II	20			150	50	200	20	
	Total				200	100	300	25	



# F.Y. M.E. (Electric Vehicle Technology) Semester -I

[503501]: Electric Vehicles

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		ning Scheme:	Credit: 04	<b>Examination Scheme:</b>	
			In Sem.Evaluation:50Marks		
				End Sem.Exam:50Marks	
				Total: 100 Marks	
		-		nines, Electrical Drives, Power	Electronics,
Micro	oproces	ssor and Microcontro	llers, Analog and Digital E	lectronics	
Cour	se Obj	ectives:			
1	To in	troduce configuration	s of EV		
2	To de	esign electric vehicle f	or various applications		
3	To se	lect appropriate moto	or and converter for EV app	lications	
4	To se	lect battery, battery in	dication system for EV app	ications	
5	To de	evelop battery charge	r for an EV		
			Course Content	S	
UN	IT-I		Introduction to I	$\mathbf{E}\mathbf{V}$	08 Hours
Introd	duction	: Past, Present & Future	e of EV, Current Major Issues	, Recent Development Trends, EV	Concept, Key
EV To	echnolo	gy, State-of-the Art E	EVs & HEVs, Comparison	of EV Vs IC Engine.	
EV S	ystem:	EV Configuration: F	fixed & variable gearing, si	ngle &multiple motor drive, In-	wheel drives
EV P	aramet	ers: Weight, size, for	ce, energy & performance	parameters.	
UNI	T-II		<b>EV Propulsion-Electri</b>	c Motor	08 Hours
Choic	ce of e	lectric propulsion sys	stem, block diagram of EV	propulsion system, concept of	EV Motors,
single	e moto	r and multi-motor c	onfigurations, fixed & va	riable geared transmission, in	wheel motor
confi	guratio	n, classification of E	V motors, Electric motors	used in current vehicle applicatio	ns, Recent EV
Motor	rs, Com	parison of Electric Moto	ors for EV applications		
UNI	T-III	F	Required Power Electronic	cs &Control	08 Hours
Comp	Comparison of EV power devices, introduction to power electronics converter, four-quadrant DC				
chop	chopper, three-phase full bridge voltage-fed inverter, soft-switching EV converters, comparison of hard-				
switc	switching and soft-switching converter, three-phase voltage-fed resonance dc link inverter, Basics of				
Micro	Microcontroller &Control Strategies				
UNI	T-IV		EV Motors		08 Hours
DC M	DC Motor: Type of wound-field DC Motor, Torque-speed characteristics, DC-DC Converter, two quadrant DC				
			= =		

Chopper, two quadrant zero voltage transition converter- fed dc motor drive, speed control of DC Motor Induction Motor Drive: Three Phase Inverter Based Induction Motor Drive, Equal Area PWM, Three Phase Auxiliary resonant snubber (ARS) Inverter Type (ZVC & ZCS), Single Phase ARS Inverter



Topology, Speed Control of Induction Motor, FOC, Adaptive Control, Model Reference Adaptive Control (MARS), Sliding mode Control

### UNIT-V Batteries and Battery management system 08 Hours

Basics: types, parameters—capacity, discharge rate, state of charge, state of discharge, depth of discharge, technical characteristics, battery pack design, properties of batteries, introduction to energy, storage requirements in hybrid and electric vehicles, battery pack development. Introduction, charging algorithm, balancing method for battery pack charging. Battery management system representation: - battery module, measurement unit block, battery equalization balancing unit, MCU Estimation unit, display unit, fault warning block, Thermal monitoring of battery unit.

UNIT-VI Battery Charging 08 Hours

Battery Chargers: Conductive (Basic charger circuits, microprocessor-based charger circuit. Arrangement of an off-board conductive charger, Standard power levels of conductive chargers, Inductive (Principle of inductive charging, Soft-switching power converter for inductive charging), Battery indication Methods Charging Infrastructure: Domestic Charging Infrastructure, Public Charging Infrastructure, Normal Charging Station, Occasional Charging Station, Fast charging station, battery swapping station, move on charge zone

### **Reference Books**

- 1 C. Chan, K.T Chau: Modern Electric Vehicle Technology, Oxford University Press Inc., New York 2001
- 2 Iqbal Hussein, Electric and Hybrid Vehicles: Design Fundamentals, CRC, Press, 2003
- Mehrdad Ehsani, Yimi Gao, Sebastian E. Gay, Ali Emadi, Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design, CRC Press, 2004.
- 4 James Larminie, John Lowry, Electric Vehicle Technology Explained, Wiley, 2003



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### $\textbf{F.Y.} \ \textbf{M.E.} \ (\textbf{Electric Vehicle Technology})$

### **Semester -I**

[503502]: Vehicle Dynamics

TH:-04Hours/Week End Sem.Evaluation:50Marks End Sem.Exam:50Marks Total: 100 Marks    Course Objectives:		Teaching Scheme: Credit: 04 Examination Scheme:					
Course Objectives:  1	TH:-04Hours/Week				In Sem.Evaluation:50Marks		
Understand the dynamics of vehicle ride under different riding condition.					End Sem.Exam:50Marks		
1 Understand the dynamics of vehicle ride under different riding condition. 2 Present a problem oriented in depth knowledge of Vehicle Dynamics. 3 Address the underlying concept and methods behind Vehicle Dynamics. 4 Calculate and refer the load and forces associated to the vehicles. 5 Analyze the behavior of the vehicles under acceleration, ride and braking    Course Contents					Total: 100 Marks		
2 Present a problem oriented in depth knowledge of Vehicle Dynamics.  3 Address the underlying concept and methods behind Vehicle Dynamics  4 Calculate and refer the load and forces associated to the vehicles.  5 Analyze the behavior of the vehicles under acceleration, ride and braking  Course Contents  UNIT-1 Bassics of Vehicle Dynamics 08Hours  History, vehicle classifications, fundamental approaches to vehicle dynamics modeling; SAE Vehicle axis system, Forces & moments affecting vehicle, Earth Fixed coordinate system, Dynamic axle loads, Equations of motion, transmission characteristics, vehicle performance, Brake proportioning, braking efficiency.  UNIT-II Acceleration Performance 08Hours  Power train components; power and traction limited acceleration; transverse weight shift; front wheel drive ves rear wheel drive vs. all-wheel drive vehicles  UNIT-III Braking Performance 08Hours  Braking force analysis; brake design and analysis; federal regulation non braking performance; antilock braking system; wheel lock-up; tire/road friction; safety and maintenance issues in braking  UNIT-IV Road Loads, Tire and Dynamics 08Hours  Wind drags and car body design, rolling resistance; break downs of total road loads; gas mileage analysis and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire force analysis; tire contact stress analysis; tire vibration analysis; tire models  UNIT-V Ride & Cornering/steering 08Hours  Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems 08Hours	Cour	rse Obj	ectives:				
Address the underlying concept and methods behind Vehicle Dynamics  Calculate and refer the load and forces associated to the vehicles.  Analyze the behavior of the vehicles under acceleration, ride and braking  Course Contents  UNIT-I Basics of Vehicle Dynamics 08Hours  History, vehicle classifications, fundamental approaches to vehicle dynamics modeling; SAE Vehicle axis system, Forces & moments affecting vehicle, Earth Fixed coordinate system, Dynamic axle loads, Equations of motion, transmission characteristics, vehicle performance, Brake proportioning, braking efficiency.  UNIT-II Acceleration Performance 08Hours  Power train components; power and traction limited acceleration; transverse weight shift; front wheel drive vs rear wheel drive vs. all-wheel drive vehicles  UNIT-III Braking Performance 08Hours  Braking force analysis; brake design and analysis; federal regulation non braking performance; antilock braking system; wheel lock-up; tire/road friction; safety and maintenance issues in braking  UNIT-IV Road Loads, Tire and Dynamics 08Hours  Wind drags and car body design, rolling resistance; break downs of total road loads; gas mileage analysis and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire force analysis; tire contact stress analysis; tire vibration analysis; tire models  UNIT-V Ride & Cornering/steering 08Hours  Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems 08Hours	1	Unde	rstand the dynamics o	f vehicle ride under differe	ent riding condition.		
Analyze the behavior of the vehicles under acceleration, ride and braking  Course Contents  UNIT-I Basics of Vehicle Dynamics 08Hours  History, vehicle classifications, fundamental approaches to vehicle dynamics modeling; SAE Vehicle axis system, Forces & moments affecting vehicle, Earth Fixed coordinate system, Dynamic axle loads, Equations of motion, transmission characteristics, vehicle performance, Brake proportioning, braking efficiency.  UNIT-II Acceleration Performance 08Hours  Power train components; power and traction limited acceleration; transverse weight shift; front wheel drive vs rear wheel drive vs. all-wheel drive vehicles  UNIT-III Braking Performance 08Hours  Braking force analysis; brake design and analysis; federal regulation non braking performance; antilock braking system; wheel lock-up; tire/road friction; safety and maintenance issues in braking  UNIT-IV Road Loads, Tire and Dynamics 08Hours  Wind drags and car body design, rolling resistance; break downs of total road loads; gas mileage analysis and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire contact stress analysis; tire vibration analysis; tire models  UNIT-V Ride &Cornering/steering 08Hours  Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems 08Hours	2	Prese	nt a problem oriented	in depth knowledge of V	ehicle Dynamics.		
Course Contents  UNIT-I Basics of Vehicle Dynamics 08Hours  History, vehicle classifications, fundamental approaches to vehicle dynamics modeling; SAE Vehicle axis system, Forces & moments affecting vehicle, Earth Fixed coordinate system, Dynamic axle loads, Equations of motion, transmission characteristics, vehicle performance, Brake proportioning, braking efficiency.  UNIT-II Acceleration Performance 08Hours  Power train components; power and traction limited acceleration; transverse weight shift; front wheel drive vs rear wheel drive vs. all-wheel drive vehicles  UNIT-III Braking Performance 08Hours  Braking force analysis; brake design and analysis; federal regulation non braking performance; antilock braking system; wheel lock-up; tire/road friction; safety and maintenance issues in braking  UNIT-IV Road Loads, Tire and Dynamics 08Hours  Wind drags and car body design, rolling resistance; break downs of total road loads; gas mileage analysis and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire force analysis; tire contact stress analysis; tire vibration analysis; tire models  UNIT-V Ride &Cornering/steering 08Hours  Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems 08Hours	3	Addr	ess the underlying cor	ncept and methods behind	l Vehicle Dynamics		
Course Contents	4	Calcu	late and refer the load	and forces associated to t	he vehicles.		
History, vehicle classifications, fundamental approaches to vehicle dynamics modeling; SAE Vehicle axis system, Forces & moments affecting vehicle, Earth Fixed coordinate system, Dynamic axle loads, Equations of motion, transmission characteristics, vehicle performance, Brake proportioning, braking efficiency.  UNIT-II	5	Analy	ze the behavior of the	vehicles under acceleration	on, ride and braking		
History, vehicle classifications, fundamental approaches to vehicle dynamics modeling; SAE Vehicle axis system, Forces & moments affecting vehicle, Earth Fixed coordinate system, Dynamic axle loads, Equations of motion, transmission characteristics, vehicle performance, Brake proportioning, braking efficiency.  UNIT-II							
History, vehicle classifications, fundamental approaches to vehicle dynamics modeling; SAE Vehicle axis system, Forces & moments affecting vehicle, Earth Fixed coordinate system, Dynamic axle loads, Equations of motion, transmission characteristics, vehicle performance, Brake proportioning, braking efficiency.  UNIT-II				<b>Course Cont</b>	ents		
axis system, Forces & moments affecting vehicle, Earth Fixed coordinate system, Dynamic axle loads, Equations of motion, transmission characteristics, vehicle performance, Brake proportioning, braking efficiency.  UNIT-II	UN	IT-I		Basics of Vehicle I	Dynamics	08Hours	
Equations of motion, transmission characteristics, vehicle performance, Brake proportioning, braking efficiency.  UNIT-II							
UNIT-II Acceleration Performance O8Hours  Power train components; power and traction limited acceleration; transverse weight shift; front wheel drive vs rear wheel drive vs. all-wheel drive vehicles  UNIT-III Braking Performance O8Hours  Braking force analysis; brake design and analysis; federal regulation non braking performance; antilock braking system; wheel lock-up; tire/road friction; safety and maintenance issues in braking  UNIT-IV Road Loads, Tire and Dynamics O8Hours  Wind drags and car body design, rolling resistance; break downs of total road loads; gas mileage analysis and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire force analysis; tire contact stress analysis; tire vibration analysis; tire models  UNIT-V Ride &Cornering/steering O8Hours  Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems O8Hours							
Power train components; power and traction limited acceleration; transverse weight shift; front wheel drive vs rear wheel drive vs. all-wheel drive vehicles  UNIT-III Braking Performance 08Hours  Braking force analysis; brake design and analysis; federal regulation non braking performance; antilock braking system; wheel lock-up; tire/road friction; safety and maintenance issues in braking  UNIT-IV Road Loads, Tire and Dynamics 08Hours  Wind drags and car body design, rolling resistance; break downs of total road loads; gas mileage analysis and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire force analysis; tire contact stress analysis; tire vibration analysis; tire models  UNIT-V Ride & Cornering/steering 08Hours  Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems 08Hours	-		f motion, transmission	on characteristics, vehicle	e performance, Brake proportioning	g, braking	
Power train components; power and traction limited acceleration; transverse weight shift; front wheel drive vs rear wheel drive vs. all-wheel drive vehicles  UNIT-III Braking Performance 08Hours  Braking force analysis; brake design and analysis; federal regulation non braking performance; antilock braking system; wheel lock-up; tire/road friction; safety and maintenance issues in braking  UNIT-IV Road Loads, Tire and Dynamics 08Hours  Wind drags and car body design, rolling resistance; break downs of total road loads; gas mileage analysis and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire force analysis; tire contact stress analysis; tire vibration analysis; tire models  UNIT-V Ride & Cornering/steering 08Hours  Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems 08Hours				Accoloration Parf	ormanca	08Hours	
drive vs rear wheel drive vs. all-wheel drive vehicles         UNIT-III       Braking Performance       08Hours         Braking force analysis; brake design and analysis; federal regulation non braking performance; antilock braking system; wheel lock-up; tire/road friction; safety and maintenance issues in braking       08Hours         UNIT-IV       Road Loads, Tire and Dynamics       08Hours         Wind drags and car body design, rolling resistance; break downs of total road loads; gas mileage analysis and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire force analysis; tire contact stress analysis; tire vibration analysis; tire models         UNIT-V       Ride & Cornering/steering       08Hours         Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover       08Hours         UNIT-VI       Chassis and Suspension Systems       08Hours			components: nower			l	
Braking Performance Braking Ferformance Braking force analysis; brake design and analysis; federal regulation non braking performance; antilock braking system; wheel lock-up; tire/road friction; safety and maintenance issues in braking  UNIT-IV Road Loads, Tire and Dynamics Wind drags and car body design, rolling resistance; break downs of total road loads; gas mileage analysis and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire force analysis; tire contact stress analysis; tire vibration analysis; tire models  UNIT-V Ride & Cornering/steering 08Hours  Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems 08Hours					electation, transverse weight shift,	Home wheel	
Braking force analysis; brake design and analysis; federal regulation non braking performance; antilock braking system; wheel lock-up; tire/road friction; safety and maintenance issues in braking  UNIT-IV Road Loads, Tire and Dynamics 08Hours  Wind drags and car body design, rolling resistance; break downs of total road loads; gas mileage analysis and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire force analysis; tire contact stress analysis; tire vibration analysis; tire models  UNIT-V Ride & Cornering/steering 08Hours  Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems 08Hours			Wheel drive vs. un		——————————————————————————————————————	08Hours	
braking system; wheel lock-up; tire/road friction; safety and maintenance issues in braking  UNIT-IV Road Loads, Tire and Dynamics  Wind drags and car body design, rolling resistance; break downs of total road loads; gas mileage analysis and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire force analysis; tire contact stress analysis; tire vibration analysis; tire models  UNIT-V Ride & Cornering/steering  Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems  08Hours			ce analysis: brake de				
UNIT-IVRoad Loads, Tire and Dynamics08HoursWind drags and car body design, rolling resistance; break downs of total road loads; gas mileage analysis and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire force analysis; tire contact stress analysis; tire vibration analysis; tire modelsUNIT-VRide &Cornering/steering08HoursRiding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient RolloverUNIT-VIChassis and Suspension Systems08Hours		_	•	•	0 1	,	
Wind drags and car body design, rolling resistance; break downs of total road loads; gas mileage analysis and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire force analysis; tire contact stress analysis; tire vibration analysis; tire models  UNIT-V Ride & Cornering/steering 08Hours  Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems 08Hours		•	, 1,			08Hours	
and driving styles; Aerodynamics Tire specifications and constructions; tire motion analysis; tire force analysis; tire contact stress analysis; tire vibration analysis; tire models    UNIT-V	Wine	d drags	and car body design,	· · · · · · · · · · · · · · · · · · ·		eage analysis	
analysis; tire contact stress analysis; tire vibration analysis; tire models  UNIT-V Ride & Cornering/steering 08Hours  Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems 08Hours							
Riding comfort; perception of vibration; vibration sources; vibration transmission to the passenger's lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems 08Hours							
lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover  UNIT-VI Chassis and Suspension Systems 08Hours	UN	IT-V		Ride &Cornering	/steering	08Hours	
Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover         UNIT-VI       Chassis and Suspension Systems       08Hours	Ridi	ng com	fort; perception of	vibration; vibration sour	ces; vibration transmission to the	passenger's	
UNIT-VI Chassis and Suspension Systems 08Hours	lowe	lower speed cornering; high speed corner; cornering bicycle model; Quasi-Static Rollover of a Rigid					
1 1	Vehicle, Quasi-Static Rollover of a Suspended Vehicle, Transient Rollover						
Suspension Kinematics, Suspension types, Solid Axles, Independent Suspensions, Anti-Sauat and Anti-	UNI	T-VI		Chassis and Suspens	ion Systems	08Hours	



Pitch Suspension Geometry, Anti-Dive Suspension Geometry, Roll Center Analysis, Suspension Dynamics, Multi-body vibration, Body and Wheel hop modes, Invariant points, Controllable Suspension

Ref	erence Books
1	Fundamentals of Vehicle Dynamics, Thomas Gillespie, SAE Publication.
2	The Multibody systems Approach to Vehicle Dynamics, Mike Blundell and Damian Harty,
	Elsevier, 2004.
3	Vehicle Dynamics, Theory and Application, Reza N. Jazar, Springer, 2009, ISBN 978-0-387-
	74243-4, e- ISBN978-0-387-74244-1.
4	Race Car Vehicle Dynamics, W.F. Milliken and D.L. Milliken, SAE,1995, ISBN1-56091-526-9.
5	Reimpell, Stoll and Betzler: The Automotive Chassis: Engineering Principles.
6	Hans Pacejka, Tire and Vehicle Dynamics, Elsevier, 2012
7	Rajesh Rajamani, Vehicle Dynamics & control, Springer.
8	R.V. Dukkipati, Vehicle dynamics, Narsova Publications.



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# F.Y. M.E. (Electric Vehicle Technology) Semester -I

[503503]: Power Electronic Converters

Teach	ning Scheme:	Credit: 04	<b>Examination Scheme:</b>				
TH:-04	4Hours/Week		In Sem.Evaluation:50Marks				
			End Sem.Exam:50Marks				
	Total: 100 Marks						
Course Pre	requisites: Knowledg	ge of Power Electronics					
Course Obj	ectives:						
1 Unde	rstand the essentials	of power conversion,					
2 Desig	gn practical non isolat	ted converters					
3 Desig	gn practical offline co	onverters					
4 Desig	gn practical isolated c	onverters					
5 Bidir	ectional converter top	pologies for Electric Vehic	es				
		Course Conten	ts				
UNIT-I		<b>Power Semiconductor</b>	08Hours				
Ideal and T	ypical Power Switc	hing Waveforms, Ideal a	nd Typical Power Device Cha	aracteristics,			
Unipolar Po	wer Devices, bipolar	Power Devices, MOS-Bip	olar Power Devices				
UNIT-II		<b>Introduction to Power C</b>	onversion	08Hours			
Converting	power with resistors	s, Converting power with	switches, the duty, buck conv	erter, boost			
converter, b	uck-boost Converter,	Input filtering, RLC filter					
UNIT-III		Non-isolated conve	08Hours				
Buck conver	rter, Boost converter,	Buck-Boost converter, and	llysis design and simulation				
UNIT-IV		Off-line Converters—the	08Hours				
Rectifier Br	idge: Capacitor selec	tion, Diode Conduction Tir	ne, Rms Current in the Capacito	or, Current			
in the Dioc	des, Input Power Fa	actor, Hold-Up Time, In-	Rush Current Power Factor C	Correction:			
Definition of Power Factor, Non-sinusoidal Signals, A Link to the Distortion, Why Power Factor							
Correction? Harmonic Limits, A Need for Storage, Passive PFC, Improving the Harmonic Content,							
The Valley-Fill Passive Corrector, Active Power Factor Correction, Constant on-time border in mode							
(BCM), fixe	(BCM), fixed-frequency continuous mode (CCM), Analytical control law.						
UNIT-V		Isolated converte	rs	08Hours			
Simulations	Simulations and practical designs of fly back converters, an isolated buck-boost, flyback waveforms						



without parasitic elements, Flyback waveforms with parasitic elements, clamping the drain excursion, designing the clamping network, two-switch flyback, simulations and practical designs of forward converters, an isolated buck converter, need for a complete core reset, a two-switch configuration, two-switch forward and half-bridge driver

UNIT-VI Bidirectional Converter Topologies for Plug-In Electric Vehicles 08Hours
Introduction, Literature Survey, Bidirectional Converters, Bidirectional AC/DC Converters for Plug-In
EV with Reduced Conduction Losses, Topology Explanation, Plug-In Charging Mode, Propulsion
Mode, Boost Operation, Buck Operation, Regenerative Braking Operation, Boost Operation, Buck

Operation, Bidirectional Battery Charger for an Electric Vehicle

l							
	Reference Books						
	1	B. Jayant Baliga, "PowerSemiconductorDevices",1st Edition, International Thompson Computer					
		Press, 1995					
	2	Christophe Basso, "Switch Mode Power Supplies: SPICE Simulations and Practical Designs", McGraw-Hill,2008					
	3	L. Ashok Kumar, S. Albert Alexander, "Power Converters for Electric Vehicles", CRC Press,&					
		Francis Group, 2021					

**Examination Scheme:** 



**Teaching Scheme:** 

# F.Y. M.E. (Electric Vehicle Technology) Semester -I

Credit: 04

[503504]: Research Methodology

TH:-04Hours/Week In Ser			In Sem.Evaluation:50Mar	rks	
				End Sem.Exam:50Marks	
			ŗ	Fotal: 100 Marks	
Cour	se Prei	requisites:			
Cour	se Obj	ectives:			
1	To de	evelop understanding	g of the basic framework of resear	ch process, various resear	ch designs
	and to	echniques.			
2	To id	entify various source	es of information for literature reviews	ew and data collection.	
3	To de	velop an understand	ing of the ethical dimensions of co	nducting applied research.	
			<b>Course Contents</b>		
UNI			Basics of research		08 Hours
			tics, Research Need, Objectives and	· ·	
-			s Methodology, Types of research	=	
		=	. Qualitative, Conceptual vs. Empir		_
			problem, Selecting the problem	•	•
_			in defining a problem. Using v		• -
			s, treatise, monographs, patents, p		areas from
		view Development o	f working hypothesis. Different too	ols for literature survey.	
UNI	T-II		Technical Writing:		08 Hours
Writin	ng The	sis: Structure and co	imponents of scientific reports, Tyj	pes of report – Technical i	reports and
thesis	, Signi	ficance, Different ste	ps in the preparation, Layout, struc	cture and Language of typic	cal reports.
Writin	ng pape	ers: types of technical	papers, Journal papers, Conference	e papers, Survey papers, Pos	ster papers,
Comp	arison,	, Structure of a surve	y, conference and journal paper. W	riting Research Proposal: 1	Importance
of res	search	funding in research	n, standard formats for different	research schemes of AIC	CTE, DST.
-		for research proposal	, how to write a research proposal.		
UNI	T-III		Assessment of research output	ıt:	08 Hours
Measi	ure for	quality of research	, citation index Researcher metric	cs (i10-index, H-index etc	c.), Article



metrics, Journal Metrics. Ethical practices in research such as plagiarism, acknowledgment etc. Commercialization of research, Copy right, royalty, Intellectual property rights and patent law, Trade related aspects of Intellectual Property Rights, patent search, drafting and filing patent, legal procedure in granting patent.

UNIT-IV Linear Programming 08 Hours

Linear Programming: Standard form of a linear programming problem-geometry of linear programming problems-definitions and theorems, linear simultaneous equations: Elimination method, Jacobi's method, Relaxation method solution of the system of pivotal reduction of a general system of equations, simplex method.

UNIT-V Linear Programming 08 Hours

Constrained Nonlinear Programming: Characteristics of a constrained problem, Classification, Basic approach of Penalty Function method, Introduction to Convex Programming Problem. Finite Difference approximations of partial derivatives.

UNIT-VI 08 Hours

Following methods with applications to particular problem of Electrical Engineering: Genetic algorithm, Simulated Annealing method, PSO, GA, SAM, Ant Colony method, ARIMA, Linear regression, Multi regression.

### References

1 Research Methodology: Methods and Techniques: C.R. Kothari



**UNIT-III** 

# F.Y. M.E. (Electric Vehicle Technology) Semester -I

[503505A]: Power Semiconductor Devices

	[503505A]: Power Semiconductor Devices				
	<b>Teaching Scheme:</b>	Credit: 05	<b>Examination Scheme:</b>		
ŗ	TH:-05Hours/Week		In Sem. Evaluation:50Marks		
			End Sem. Exam:50Marks		
			Total: 100 Marks		
Cours	se Prerequisites: Knowled	lge of Power Electron	ics		
Cours	se Objectives:				
1	To identify various powe application.	r semiconductor device	es and their ratings for various power	er electronic	
2	To understand the static semiconductor devices	and dynamic characte	eristics of voltage and current contr	folled power	
3	To enable the students, t Applications	he knowledge of selec	ction of devices for different power	electronics	
4	To understand the control	and Gate Drive require	ements for different power devices.		
		Course Cor	ntents		
UNIT	`-I	Power Dic	odes	08Hours	
On-sta	ate losses, switching char	racteristics-turn-on trai	nsient, turn-off transient and rever	se recovery	
transi	transient, Schottky diodes, series and parallel connections of diodes, snubber requirements for diodes,				
diode	diode snubber.				
UNIT	`-II	Power BJ	T'S	08Hours	
On sta	ate losses, switching charac	teristics, resistive switch	thing specifications, clamped inductive	we switching	

Basic structure and operation, GTO switching characteristics, GTO turn-on transient, GTO turn-off transient, minimum on and off state times, gate drive requirements, maximum controllable anode current, over current protection of GTO'S.

specifications, turn-on transient, turn-off transient, storage time, base drive requirements, switching

**Gate Turn off Thyristor (GTO)** 

losses, device protection-snubber requirements for BJT'S and snubber design-switching aids.

08Hours



UNIT-IV 08Hours

Basic structure, V-I characteristics, turn-on process, on state operation, turn-off process, switching characteristics, resistive switching specifications, clamped inductive switching specifications - turn-on transient and di/dt limitations, turn-off transient, turn off time, switching losses, effect of reverse recovery transients on switching stresses and losses - dv/dt limitations, gating requirements, gate charge-ratings of MOSFET'S,FBSOA and RBSOA curves, device protection—snubber requirements, MOSFET drivers and protection, Miller region

### UNIT-V Insulated Gate Bipolar Transistors (IGBT'S) 08Hours

Basic structure and operation, latch up IGBT, switching characteristics, resistive switching specifications, clamped inductive switching specifications - IGBT turn-on transient, IGBT turn off transient- current tailing-gating requirements -ratings of IGBT'S, FBSOA and RBSOA curves, switchinglosses-minimumonandoffstatetimes-switchingfrequencycapability—overcurrent Protection of IGBT'S, short circuit protection, snubber requirements and snubber design. IGBT drivers and protection, Active clamping.

UNIT-VI New Power Semiconductor Devices 08Hours

MOS gated thyristors, MOS controlled thyristors or MOS GTO'S, base resistance-controlled thyristors, emitter switched thyristor, thermal design of power electronic equipment, modeling and simulation, heat transfer by conduction, transient thermal impedance-heat sinks, heat transfer by radiation and convection-heat sink selection for power semiconductor devices

# Reference Books Ned Mohan, Tore M. Undeland, William P. Robbins, "Power Electronics Converters, Applications, and Design", 3<sup>rd</sup> Edition. Wiley India Pvt Ltd, 2011. G. Massobrio, P. Antognetti, "Semiconductor Device Modeling with Spice", McGraw-Hill,2nd Edition, 2010. B. Jayant Baliga, "Power Semiconductor Devices", 1stEdition, International Thompson Computer Press, 1995 V. Benda, J. Gowar, and D. A. Grant, "Discrete and Integrated Power Semiconductor Devices: Theory and Applications", John Wiley & Sons, 1999 Benda, J. Gowar, and D.A. Grant, "Discrete and Integrated Power Semiconductor Devices: Theory and Applications", John Wiley & Sons, 1999.



# F.Y. M.E. (Electric Vehicle Technology) Semester -I

[503505B]: Automotive Electronics for EVs

Tea	ching Scheme:	Credit: 05	<b>Examination Scheme:</b>		
TH:	-05Hours/Week		In Sem. Evaluation:50Marks		
			End Sem. Exam:50Marks		
			Total: 100 Marks		
Course P	Course Prerequisites: Basic Electronics Engineering, Power Electronics, Electric Vehicle mobility				
Course O	bjectives:				
1 Un	derstand the electrical a	and electronic systems in vo	ehicles		
2 Un	derstand the principles	of networking			
3 Ex	plain requirements and	types of bus systems			
4 Co	mprehend the lighting	systems in vehicles			
5 Un	derstand the auxiliaries	and chassis electric systen	ns in automobiles.		
		Course Conten	ts		
UNIT-I	Electr	ical And Electronic System	ms in the Vehicle	8Hours	
Overview	Electronic diesel cont	rol, Lighting technology, e	electronic stability program, Ada	aptive cruise	
control, I	nfotainment System.	Network topology & org	ganization, OSI reference mod	del, Control	
mechanisı	ns.				
UNIT-II		Automotive networ	king	8Hours	
Cross-sys	tem functions, Require	ments for bus systems, Clas	sification of bus systems, Applic	ations in the	
vehicle, co	oupling of networks, Ex	xamples of networked vehi-	cles system.		
UNIT-II		Bus systems		8Hours	
CAN bus	Applications, Topolo	gy, Data transmission syst	em, CAN protocol, data transfe	er sequence,	
standardiz	ation, characteristics.	bus: Introduction, feature	es, data transfer, administrative	e functions,	
Application	on layer Bluetooth: Ove	rview, applications, Blueto	oth versions, transmission techno	ology, power	



classe	classes, topology, physical data channel, physical connections.				
UNIT	T-IV	Lighting system	8Hours		
Archit	Architecture. Lighting fundamentals Lighting circuits, Gas discharge and LED lighting, Case studies,				
Diagn	nosing l	lighting system faults, Advanced lighting technology, new developments in lighti	ng Systems.		
UNIT	<b>T-V</b>	Auxiliaries in vehicles	8Hours		
Wind	screer	washers and wipers, signaling circuits, Other auxiliary systems, Case studies, I	Diagnosing		
auxili	iary sys	stem faults Advanced auxiliary systems technology, new developments in auxilia	ry systems.		
UNIT	T-VI	Chassis Electrical systems	8Hours		
Chass	sis Ele	ectrical systems. Anti-lock brakes, Active suspension, Traction control,	Automatic		
Transi	missio	n, Other chassis electrical systems, Case studies, Diagnosing chassis electrical sys	stem faults,		
Advar	nced cl	nassis systems technology, new developments in chassis electrical systems.			
Refer	ence E	Books			
1 1	Robert	Bosch Gmb H, "Bosch Automotive Electrics and Automotive Electronics",	5th Edition.		
	John W	Viley & Sons Ltd, 2007.			
2	Williar	m B. Ribbens, "Understanding Automotive Electronics", 6th Edition, Elsevier, 2003	•		

# F.Y. M.E. (Electric Vehicle Technology) Semester -I

[503505C]: Control Systems and Instrumentation in Automotive Systems

<b>Teaching Scheme:</b>			Credit: 05	<b>Examination Scheme:</b>	
	TH:-05	Hours/Week		In Sem. Evaluation:50Marks	
				End Sem. Exam:50Marks	
	Total: 100 Marks				
Cou	rse Pre	requisites: Control S	System, Basic Electronics	s Engineering.	
Cou	rse Obj	ectives:			
1	To di	scuss the sensor and	measuring system of aut	omobile.	
2	To in	fer the knowledge of	various automotive stan	dards and Protocols.	
3	To el	aborate the design of	basic modeling and con	trol scheme for automotive systems	S.
			Course Cont	ents	
UNI	T-I		Control System in	Vehicle	8Hours
Cont	trol syst	em representation fo	or vehicles, controllabili	ty and stability analysis. Closed le	oop Electric
Veh	icle syst	tem. Speed control te	ahniquas aantral systam		
UNIT-II Measurement Analysis 8Hour			chinques control system	•	
UNI	T-II	-			8Hours
		nt characteristics, sel	Measurement A		
Meas		nt characteristics, sel	Measurement A	nalysis	
Meas EV s	suremer	nt characteristics, sel	Measurement A	nalysis  of considerations, measurement of h	
Meas EV s	suremer system <b>T-III</b>		Measurement An ection criteria, reliability  Digital Control S	nalysis  of considerations, measurement of h	armonics in 8Hours
Meas EV s UNI	surements system <b>T-III</b> oduction ementat	of linear control s	Measurement An ection criteria, reliability  Digital Control S ystem analysis design a inear equation solutions,	ystems pproaches, as well as digital con z-transforms, and Laplace transforms	8Hours trol system orms, linear
Meas EV s UNI Intro imple Cont	surements system  T-III  duction ementate troller description	of linear control sylion. Linearization, lilesign, optimum con	Measurement An ection criteria, reliability  Digital Control S  ystem analysis design a inear equation solutions, trol, and digital implem	ystems pproaches, as well as digital con z-transforms, and Laplace transfo	8Hours trol system orms, linear
Meas EV s UNI Intro imple Cont	surements system  T-III  duction ementate troller description	of linear control sylion. Linearization, lilesign, optimum con	Measurement An ection criteria, reliability  Digital Control S ystem analysis design a inear equation solutions,	ystems pproaches, as well as digital con z-transforms, and Laplace transfo	8Hours trol system orms, linear

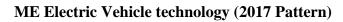


EV	EV design, building, operation, application, and computer systems for controlling, sensing, and				
proc	processing information. From quantum technologies to energy-efficient communications networks.				
UNI	IT-V Automotive Instrumentation 8Hours				
Basi	c sensor	arrangement, types of sensors such as oxygen sensors, crank angle, position sen	sors, Fuel		
	_	ehicle speed sensors, flow sensor, temperature, air, mass flow sensors, throttle	le position		
sense	or, solei	noids etc			
UNI	T-VI	Application of EV and ECU	8Hours		
Intro	duction	of automobile system, current trends in automobiles with emphasis on increas	ing role of		
elect	ronics a	and software, overview of generic automotive control ECU functioning			
Refe	Reference Books				
1	1 Automotive Electrical Equipment by Young A.P., Griffiths, ELBS& New Press, 1999.				
2	2 Understanding Automotive Electronic by Bechhold, SAE,1998.				
3	Under	standing Automotive Electronics by William B. Ribbens, Butterworth Heinemann	Woburn,6th		

# F.Y. M.E. (Electric Vehicle Technology) Semester -I

[503506]: Lab Practice-I Electric Vehicles Lab

	Teaching Scheme: Lab:04 Hours/Week	Credit:04	Examination Scheme: TW Evaluation: 50 Marks OR/ Presentation: 50 Marks
Con	rse Prerequisites: Electrica	   Machines I & II   Dower ale	Total: 100 Marks
	rse Objectives:	i Waciiiies-iⅈ, Fowei elec	ctronics
1	To understand the Electric	vehicle model.	
2	To develop Battery manag	gement system.	
3	To apply knowledge gain used for EV.	ed about EV drives& speed	control of various different type of motors
		Lab Contents	
Elec	tric Vehicle Lab		
1	To study about the controll	er and its output of Electrica	al Vehicle
2	Study and obtain the param	eters of Electric vehicle trai	ner at no load.
3	Study and obtain the speed	of Electric vehicle trainer a	t load.
4	To study the Fault analysis	in BLDC motor of Electrica	al Vehicle.
5	Study of Charging &discha	rging characteristic of BMS	(Battery Management System).
6	Study of cell balancing phe	nomenon of Battery Manag	ement System(BMS)
7	Study load characteristic of	PMSM motor	





8	Study of load characteristic of PMDC Motor.
9	Study of load characteristic of BLDC Motor.

# F.Y. M.E. (Electric Vehicle Technology) Semester -II

[503507]: Embedded Systems

Tea	ching Scheme:	Credit: 04	<b>Examination Scheme:</b>	
TH:	04Hours/Week		In Sem.Evaluation:50Marks	
			End Sem.Exam:50Marks	
			Total: 100 Marks	
Course I	Prerequisites: Electric	al Circuits, Electrical Macl	nines, Electrical Drives, Power	Electronics,
Microproc	essor and Microcontrol	lers, Analog and Digital Ele	ectronics	
Course O	bjectives:			
1 To	familiarize the concept	of embedded system		
2 To	identify various process	ing element so embedded sy	stem and their structure	
3 To	introduce various memo	ory elements used in embedd	ed systems	
4 To	understand various inter	rfacing devices used with em	bedded systems	
5 To	introduce the concept of	f Real Time Operating System	ms	
1				
		Course Content	ts ·	
UNIT-I		Introduction		08Hours
Embedded	d systems overview-des	ign challenge-optimizing m	etrics-processor technology-IC tech	nnology
UNIT-II		Processing Elemen	nts	07Hours
Custom si	ngle purpose processor	r design-RT level custom s	ingle purpose processor design-	- optimizing
custom sir	ngle purpose processors-	-General purpose processor '	s software: architecture, operation,	programmers
view and d	evelopment environment-	ASIPs-selecting a microprocess	sor- general purpose processor des	ign.
UNIT-III		Memory		09Hours



Introduction-memory write-ability and storage permanence, common memory types- composing memory-memory hierarchy and caches-advanced RAM. Interfacing 09Hours **UNIT-IV** Introduction-communication basics-microprocessor interfacing: I/O addressing, interrupts, DMA-Arbitration- multilevel bus architectures-advanced communication principles-serial protocols-parallel protocols-wireless protocols-Standard single purpose processor's peripherals: timers, counters, watchdog timers, UART, PWM, LCD controllers, keypad controllers, stepper motor controllers, ADC and RTC. **Introduction to Real-Time Operating Systems UNIT-V** Software architectures, real-time systems, Basic functions of RTOS kernel, tasks and states, tasks and data, semaphores and shared data, Message Ques, Mailboxes and Pipes **Reference Books** Frank Vahid and Tony Givargis, Embedded system design: A unified hardware/Software introduction, Third edition, John Wiley & sons, 2010. 2 Embedded System Premier, David E Simon, Addison Wesley Embedded System 2nd Edition by Raj Kamal, Tata McGraw-Hill Education 3 4 Wayne Wolf, Computers as Components: Principles of Embedded Computing System Design, Morgan KaufmanPublishers,2008. Santanu Chattopadhyay, Embedded system Design, PHI LearningPvt.Ltd.,2010 5 Steave Heath, Embedded system Design, Second edition, 2003 6 7 Daniel D. Gajski, Samar. Abdi, Andreas. Gerstlauer Embedded system design: Modeling, Synthesis and verification, Springer, 2009 8 Jonathan. W. Valvano, Embedded Microcomputer systems: Real Time Interfacing, Third edition, Cengagelearning,2012 9 Frank Vahid and Tony Givargis, Embedded system design: A unified hardware/Software introduction, Third edition, John Wiley & sons, 2010.



# F.Y. M.E. (Electric Vehicle Technology) Semester -II

[503508]: Battery Management System

	Teach	ing Scheme:	Credit: 04	<b>Examination Scheme:</b>	
TH: 04Hours/Week		Hours/Week		In Sem.Evaluation:50Marks	
				End Sem.Exam:50Marks	
				Total: 100 Marks	
Cour	se Prei	requisites: Electrica	l Circuits, Electrical Mach	ines, Electrical Drives, Power	Electronics,
Micro	process	sor and Microcontro	llers, Analog and Digital El	ectronics	
Cour	se Obje	ectives:			
1			attery Management System p	arts	
2	To und	derstand basic inform	ation about batteries		
3	To me	easure different batter	y parameters		
4	To est	imate state of charge	e of the battery		
5	To est	imate state of health	of the battery		
	I.				
			<b>Course Content</b>	S	
UNIT	Γ <b>-I</b>		Battery Management Syste	em parts	06Hours
The I	Power	Module (PM), The	battery, The DC/DC cor	verter, load, communication	channel,
Exam	ples of	Battery Managemen	t Systems, Comparison of l	BMS in a low-end and high-end	l shaver,
Comp	oarison	of BMS into types or	f cellular phones		
UNIT	T-II	Basic infor	mation on batteries and Li	thium-Ion Batteries	08Hours



Battery systems, Definitions Battery design, Battery characteristics, General operational mechanism of batteries, Basic thermodynamics, Kinetic and diffusion over potentials, Double-layer capacitance, Battery voltage, Battery Operation, Battery Construction, Battery Chemistry, Safety Longevity, Performance, Integration

### UNIT-III Measurement of battery parameters 08Hours

Cell Voltage Measurement, Current Measurement, Current Sensors Current Sense Measurements, Synchronization of Current and Voltage, Temperature Measurement, Measurement Uncertainty and Battery Management, System Performance

### UNIT-IV Battery Management System Functionality 08Hours

Charging, Strategies, CC/CV Charging Method, Target Voltage Method, Constant Current Method, Thermal Management, Operational Modes, Balancing Strategies, Balancing Optimization, Charge Transfer Balancing, Flying Capacitor, Inductive Charge Transfer Balancing, Transformer Charge Balancing, Dissipative Balancing, Balancing Faults, SOC Algorithms: Challenges, Definitions, Coulomb Counting, SOC Corrections, OCV Measurements, Temperature Compensation, Kalman Filtering, Other Observer Methods

### UNIT-V State-of-Health Estimation Algorithms 08Hours

State of Health, Mechanisms of Failure, Predictive SOH Models Impedance Detection, Passive Methods, Active Methods, Capacity Estimation, Self-Discharge Detection Parameter Estimation, Dual-Loop System, Remaining Useful Life Estimation

### UNIT-VI Fault Detection 08Hours

Overview, Failure Detection, Overcharge/Overvoltage, Over-Temperature, Overcurrent Battery Imbalance/Excessive Self-Discharge, Internal Short Circuit Detection, Detection of Lithium Plating, Venting Detection, Excessive Capacity Loss, Reaction Strategies

### **Reference Books**

- H. J. Bergveld, "Battery management systems: Design by Modelling" University Press Facilities, Eindhoven,2001
- 2 Phillip Weicker, "A Systems Approach to Lithium-Ion Battery Management", Artech house, 2014
- 3 Gregory L. Plett," Battery Management Systems: Battery Modeling", Artechhouse, 2015
- M. Barak (Ed.), T. Dickinson, U. Falk ,J.L. Sudworth, H.R. Thirsk, F.L. Tye, "Electrochemical Power Sources: Primary& Secondary Batteries", IEE Energy Series 1, A. Wheaton &Co, Exeter, 1980.



# F.Y. M.E. (Electric Vehicle Technology) Semester -II

[503509]: Charging Systems and Infrastructure

[505507]. Charging Systems and Intrastructure				
Te	eaching Scheme:	Credit: 04	<b>Examination Scheme:</b>	
TH: 04Hours/Week			In Sem.Evaluation:50Marks	
			End Sem.Exam:50Marks	
			Total: 100 Marks	
Course	Prerequisites: Knowled	ge of Power Electronics		
Course	Objectives:			
1 T	o describe vehicle electri	fication and impact of char	ging strategies.	
2 T	o discuss the influence o	f EVs on power system.		
3 T	o discuss about the evalu	ation of the charging and f	acility planning.	
l l				
		Course Conten	ts	
UNIT-I		Basics of Charge	rs	08Hours
Types of	f Chargers, Charging pov	ver components		
UNIT-I				08Hours
Selection	n and design of compone	nts.	·	
UNIT-I	II	<b>Charging and Chargers</b>	Standard	08Hours



Inter	International standards, Bi-directional chargers, On-board chargers				
UNI	T-IV	Charging Infrastructure	08Hours		
Cha	Charging infrastructure design, Charging infrastructure requirements				
UNI	T-V	Charging Policies	08Hours		
Road	lmap, di	fferent charging policies and government initiative sand challenges			
UNI	T-VI	Converters for Plug-in EV	08Hours		
Bidi	rectiona	al AC/DC Converters for Plug-In EV with Reduced Conduction Losses,	Topology		
Exp	lanation	, Plug-In Charging, Bidirectional Battery Charger for an Electric Vehicle			
Refe	erence I	Books			
1	Mohan	nmad S.Alam, Reji Pillai, Murugesan Navaneetha Krishnan, Developing Charging In	nfrastructure		
	and Te	chnologies for Electric Vehicles, IGI Global			
2	Ashok Kumar, S. Albert Alexander," Power Converters for Electric Vehicles", CRC Press, Taylor				
	& Fran	ncis Group, 2021.			

# F.Y. M.E. (Electric Vehicle Technology) Semester -II

### [503510A]: Energy Storage Systems and Management

	Teaching Schemo TH: 05Hours/We		Examination So In Sem.Evaluat End Sem.Exam Total: 100 Mar	ion:50Marks a:50Marks
Cour	rse Prerequisites:			
Cour	rse Objectives:			
1	To understand wo	orking of different types	of electric vehicles.	
2	To explain the ba	ttery parameters.		
3	To understand different types of batteries.			
4	To illustrate battery charging and modeling			
5	To introduce novel and alternate energy sources.			
	-	<u> </u>		
		Cour	se Contents	
UNI	T-I	Types of	Electric Vehicle	08Hours



Battery electric vehicles, The IC engine/electric hybrid vehicle, fuel electric vehicles, Electric vehicles using supply lines, Solar powered vehicles, Electric vehicles which use flywheels or super capacitors, Electric Vehicles for the Future

UNIT-II Battery Parameters 08Hours

Electrochemical Batteries, Cell and battery voltages, Charge (or amp-hour) capacity, Energy stored, Specific energy, Energy density, Specific power, amp-hour (or charge) efficiency, Energy efficiency. Self-discharge rates, Battery geometry, Battery temperature, Battery life and number of deep cycles.

UNIT-III Types of Batteries 08Hours

Lead Acid Batteries, Nickel-based Batteries: Introduction, Nickel cadmium, Nickel metal hydride batteries, Sodium-based Batteries, Lithium Batteries, Metal Air Batteries,

UNIT-IV Battery Charging and Modeling 08Hours

Battery Charging, Battery chargers, Charge equalization, The Designer's Choice of Battery, Use of Batteries in Hybrid Vehicles, Internal combustion/battery electric hybrids, Battery/battery electric hybrids, Combinations using flywheels, Complex hybrids, Battery Modeling, the purpose of battery modeling, Battery equivalent circuit, Modelling battery capacity, Simulation a battery at a set power, Calculating the Peukert Coefficient, Approximate battery sizing

UNIT-V Alternative and Novel Energy Sources and Stores: 08Hours

Introduction, Solar Photovoltaic, Wind Power, Flywheels, Ultracapacitors, Super Capacitors, Supply Rails,

UNIT-VI Hydrogen Fuel Cells 08Hours

Hydrogen Fuel Cells: Basic Principles, Hydrogen Storage I: Storage as Hydrogen, Hydrogen Storage II: Chemical Methods

### **Reference Books**

- James Larminie Oxford Brookes University, Oxford, UK John Lowry Acenti Designs Ltd.,UK, Electric Vehicle Technology Explained
- M. Barak (Ed.), T. Dickinson, U.Falk, J.L. Sudworth, H.R. Thirsk, F.L. Tye," Electrochemical Power Sources: Primary & Secondary Batteries", IEE Energy Series 1, A. Wheaton &Co, Exeter, 1980.
- Mehrdad Ehsani, Yimi Gao, Sebastian E. Gay, Ali Emadi, Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design, CRC Press, 2004



# F.Y. M.E. (Electric Vehicle Technology) Semester -II

### [503510B]: Electronic System Design

	Teaching Scheme: TH: 05Hours/Week	Credit: 05	Examination Scheme: In Sem.Evaluation:50Marks End Sem.Exam:50Marks		
			Total: 100 Marks		
Cou	rse Prerequisites:				
Cou	rse Objectives:				
1	To discuss different design parameters and requirement of power supplies.				
2	To elaborate about the design of filters and regulators.				
3	To elaborate about the design of inverter and driver circuits.				
4	4 To discuss about design of UPS.				
	Course Contents				



UNIT-I	Design of Power Supplies:	08Hours			
IC based lin	IC based linear power supplies, Switched mode power supply topologies - forward, Fly back, Push – pull,				
Bridge, SM	Bridge, SMPS IC's, Magnetic component requirement and design,				
UNIT-II	VIT-II Design of Filters and Regulators				
Filter design	n, Voltage regulation, Load regulation, EMI/EMC considerations, Design of PI c	ontroller.			
UNIT-III	Design of Inverter and driver circuit	08Hours			
Design of In	nverter, Design of driver circuit with isolation and protection for single phase h	alf – bridge			
inverter and	full-bridge inverter, PWM circuit design for single-phase and three-phase inverter	erter, Power			
circuit desig	n.				
UNIT-IV	Protection and Selection	08Hours			
Protection of	circuit needs and heat sink design, Selection of ratings of components and power	er devices,			
Signal sens	ing and its conditioning.				
<b>UNIT-V</b>	Design of UPS	08Hours			
Design of U	PS system: Type of UPS, Battery charger design, Selection of battery bank, Ah ca	apacity,			
Back – up t	ime, Topologies of UPS, Redundancy, Bypass mechanism, Controller features,	Harmonics			
at supply si	at supply side and load sides, Applications.				
UNIT-VI Sensors and Actuators 08Hours					
UNIT-VI	Sensors and Actuators	08Hours			
	Sensors and Actuators  , types of sensors, sensor characteristic, sensor response, sensor error, Redu				
	types of sensors, sensor characteristic, sensor response, sensor error, Redu				
Introduction	types of sensors, sensor characteristic, sensor response, sensor error, Redu				
Introduction	types of sensors, sensor characteristic, sensor response, sensor error, ReduCU				
Introduction sensors in E	types of sensors, sensor characteristic, sensor response, sensor error, ReduCU	undancy of			
Introduction sensors in E  Reference I  1 Manol	n, types of sensors, sensor characteristic, sensor response, sensor error, Redu CU Books	undancy of			

# F.Y. M.E. (Electric Vehicle Technology) Semester -II

[503510C]: Thermal Management of EV systems

	<b>Teaching Scheme:</b>	Credit: 05	<b>Examination Scheme:</b>
	TH: 05Hours/Week		In Sem.Evaluation:50Marks
			End Sem.Exam:50Marks
			Total: 100 Marks
Cour	se Prerequisites: Engineeri	ng Physics, Basic Electrica	l& Electronics, Analog & digital electronics,
Powe	r electronics.		
Cour	se Objectives:		
1	To understand thermal ma	nagement of electronics.	
2	To understand the importance of thermal resistance network.		
3	To understand thermal management of microelectronic packages.		
4	To comprehend the concepts of cooling techniques.		
5	To explain thermal manag	ement systems.	



	Course Contents				
UNIT-I	UNIT-I Introduction to thermal management of Electronics				
Semiconduc	ctor Technology Trends, Temperature Dependent Failures Temperature Dependent	nt Electrical			
Failures, In	portance of Heat Transfer in Electronics, Thermal Design Process				
UNIT-II	Thermal Resistance Network	09Hours			
Thermal Re	esistance Concept, Series Thermal Layers, Parallel Thermal Layers General	Resistance			
	hermal Contact Resistance, Interface Materials, Spreading Thermal Resistance	e, Thermal			
	of Printed Circuit Boards (PCBs)	0777			
UNIT-III	Fins and Heat Sinks	07Hours			
	n, Infinitely Long Fin, Adiabatic Fin Tip Convection and Radiation from Fin Ti				
-	e Fin Tip Fin Thermal Resistance, Effectiveness, and Efficiency with Variation of the Fin Tip Fin Thermal Resistance, Effectiveness, and Efficiency with Variation of the Fin Tip Fin Thermal Resistance, Effectiveness, and Efficiency with Variation of the Fin Tip Fin Thermal Resistance, Effectiveness, and Efficiency with Variation of the Fin Tip Fin Thermal Resistance, Effectiveness, and Efficiency with Variation of the Fin Tip Fin Thermal Resistance, Effectiveness, and Efficiency with Variation of the Fin Tip Fin Thermal Resistance, Effectiveness, and Efficiency with Variation of the Fin Tip Fin Thermal Resistance, Effectiveness, and Efficiency with Variation of the Fin Tip Fin Thermal Resistance, Effectiveness, and Efficiency with Variation of the Fin Tip Fin				
	eat Sink Thermal Resistance, Effectiveness, and Efficiency, Heat Sink Manufactur	ing			
Processes.					
UNIT-IV	Advanced Cooling Technologies	10Hours			
	llary Limit, Boiling Limit. Sonic Limit, Entrainment Limit, Other Heat Pipe Per	rformance			
	t Pipe Applications in Electronic Cooling, Thermosyphons, Liquid Cooling				
UNIT-V	Thermal Specification of Microelectronic Packages	10Hours			
-	of Packaging, Packaging Types, Specifications of Microelectronic Packages, Ju				
Air Therm	al Resistance, Junction-to-Case and Junction-to-Board, Thermal Resistances	s, Package			
Thermal Ch	aracterization Parameters, Parameters Affecting Thermal Characteristics of a Pack	kage			
Reference l	Books				
1 Youne	1 Younes Shabany, "Heat Transfer: Thermal Management of Electronics" 2010, CRC Press.				
2 Jerry S	Jerry Sergent, Al Krum, "Thermal Management Handbook: For Electronic Assemblies Hardcover",				
1998,	1998, Mc-Graw- Hill.				
3 "Vehic	cle thermal Management Systems Conference Proceedings",1stEdition ;2013	6, Coventry			
Techn	Techno centre, UK				
4 T.Yon	T.Yomi Obidi," Thermal Management in Automotive applications", 2015, SAE International				

# F.Y. M.E. (Electric Vehicle Technology) Semester -II

[503511]: Lab Practice-II: Power-train Laboratory

Teaching Scheme: TH: 04Hours/Week		Credit: 04	Examination Scheme: TW:50 Marks
			OR/Presentation: 50 Marks
			Total: 100 Marks
Cour	se Prerequisites: Electrical	Machines-I&II, Power electron	ics.
Cour	se Objectives:		
1	1 To study conventional vehicle fuel economy and efficiency.		
2	To understand the working of transmission control module.		
3	3 To study hybrid electric vehicle (HEV) multimode reference application.		
4	4 To understand hybrid electric vehicle (HEV)input power-split reference application		
5	Study of Electric Vehicle reference application using MATLAB		



	Lab Contents			
Pov	Power train Laboratory			
1	Study of Conventional Vehicle Spark-Ignition Engine Fuel Economy and Emissions using			
	MATLAB			
2	Study of Conventional Vehicle efficiency using MATLAB			
3	Study of conventional vehicle reference application to optimize the transmission control module			
	(TCM) shift schedules using MATLAB			
4	Study of hybrid electric vehicle (HEV)multimode reference application using MATLAB			
5	Study of conventional vehicle reference application to optimize the transmission control module			
	(TCM) shift schedules to design control algorithms			
6	Study of conventional vehicle reference application to optimize the transmission control module			
	(TCM) shift schedules to assess the impact of power train changes, such as an engine O rgear ratio,			
	on performance, fuel economy, and emissions.			
7	Study of hybrid electric vehicle (HEV) input power-split reference application using MATLAB.			
8	Study of HEV P0 reference application using MATLAB			
9	StudyofHEVP1reference application using MATLAB			

# F.Y. M.E. (Electric Vehicle Technology) Semester -II

[503512]: Seminar-I

Teaching Scheme:	Credit: 04	<b>Examination Scheme:</b>
TH: 04Hours/Week		TW:50 Marks
		OR/Presentation: 50 Marks
		Total: 100 Marks

Seminar I shall be on the state-of-the-art topic of student's own choice based on relevant specialization approved by an authority. Topic should cover the advancement on the technology under specialization. The content of seminar report may include basic theory, concept, schematics, models, methods, economics, merits, demerits etc. relevant to the selected topic of seminar. A student should study enough papers from referred journals related to the topic in consultation with the guide. A guide should maintain



a weekly record of discussion related to the topic. The student shall submit the seminar report in standard format, duly certified by the concerned Guide and Head of the department/institute for satisfactory completion of the work.

# F.Y. M.E. (Electric Vehicle Technology) Semester -III

### [603501]: Advanced Battery Technology for Electrical Vehicles

	Teaching Scheme:	Credit: 04	Examination Scheme:			
	TH: 04Hours/Week		In Sem.Evaluation:50Marks			
			End Sem.Exam:50Marks			
			Total: 100 Marks			
Cour	Course Prerequisites:					
Cour	se Objectives:					
1	To understand electrical ve	chicle operation& batter	y basics			
2	2 To study the electric vehicle battery requirement and battery efficiency					



3	To explain electric vehicle battery charging methods				
4	To understand electric vehicle fast charging discharging behavior				
5	To ur	nderstand electric vehicle battery performance			
		Course Contents			
UNI	Γ-Ι	ELECTRIC V EHICLE BATTERIES	08 Hours		
Electi	ric Ve	hicle Operation, Battery Basics, Introduction to Electric Vehicle Batteries	, Fuel Cell		
		, Choice of a Battery Type for Electric Vehicles			
UNIT	Γ-II	ELECTRIC VEHICLE BATTERY EFFICIENCY	08 Hours		
		VRLA Battery Formation on Electric Vehicle Performance, Regenerative Braki			
Vehic	ele Boo	dy and Frame, Fluids, Lubricants, and Coolants, Effects of Current Density	on Battery		
		Effects of Excessive Heat on Battery Cycle Life, Battery Storage, The Lithium-	ion Battery,		
		ttery Pack Design			
UNIT		ELECTRIC VEHICLE BATTERY CAPACITY	08 Hours		
		acity, The Temperature Dependence of Battery Capacity, State of Charge of a VR			
_	•	scharge Testing of VRLA Batteries, Battery Capacity Recovery, Definition of Ni	•		
		-ion Battery Capacity, Battery Capacity Tests, Energy Balances for the Electric V			
UNIT		ELECTRIC VEHICLE BATTERY CHARGING	08 Hours		
_		MH Batteries, Rate of Charge, Effect on Charge, Acceptance Efficiency of Trace			
		ronmental Influence son Charging, Charging Methods for NiMH Batteries	s, Charging		
		, Battery Pack Corrective Actions	00.44		
UNIT		ELECTRIC VEHICLE BATTERY FAST CHARGING	08 Hours		
		off-board charging, The Fast-Charging Process, Fast Charging Strategies, The I			
	_	on, Using Equalizing/Leveling Chargers, Inductive Charging, Making Rechar			
_		ing of Electric Vehicles Using Fast Charging, Electric Vehicle Speedometer	Calibration.		
	less Ch		00.77		
UNIT		ELECTRIC VEHICLE BATTERY DISCHARGING	08 Hours		
		Performance Management System, BPMS Thermal Management System,			
	Charging Control, High-Voltage Cabling and Disconnects, Safety in Battery Design, Battery Pack				
	Safety, Electrolyte Spillage and Electric Shock, Charging Technology, Electrical Insulation Breakdown				
Detec	Detection, Electrical Vehicle Component Tests, Building Standards, Ventilation				
Dofor	aon oo T	Doolea			
	rence I	c vehicle battery systems by Sandeep Dhameja, Newnes Publishing, 2002			
1	Electric vehicle battery systems by Sandeep Dhameja, Newnes Fubrishing, 2002				

# F.Y. M.E. (Electric Vehicle Technology) Semester -III

[603502]: Advanced Electrical Machines

Teaching Scheme:	Credit: 04	Examination Scheme:		
TH: 04Hours/Week		In Sem.Evaluation:50Marks		
		End Sem.Exam:50Marks		
		Total: 100 Marks		
Course Prerequisites:				
Course Objectives:				
1 To understand electrical BLDC motor				



	1 4 1 1 4 1 1 0 1 1 0					
3 To ur	3 To understand Switched Reluctance Motors					
	Course Contents					
UNIT-I	BLDC Motor	08 Hours				
Permanent	Magnet materials, Permanent Magnet Brushless DC Motors-Construction, o	perating				
principle& f	eatures of permanent magnet brushless (PMBL)motors, various types of PMBL	motors,				
magnetic ci	rcuit model, armature reaction, derivation of emf and torque equation, types	of emf				
generated, p	erformance characteristics, control of PMBLDC motors,					
UNIT-II	Stepper Motor	08 Hours				
Concept of	Stepper Motors, types and operating principle of stepper motors, static and	l dynamic				
characteristi	cs of stepper motors, stepper motor converters					
UNIT-III	Switched Reluctance Motors	08 Hours				
Construction	n as well as operating principle and features of switched reluctance motors (SRM)	), equivalent				
magnetic cir	cuit, inductance profile, derivation of torque equation and factors, affecting torque	ue.				
UNIT-IV	Control Strategies of Switched Reluctance Motors	08 Hours				
Performance	e characteristics, control of SRM, various types of converters, vector diagram, co	ontrol and				
topological a	advancements of synchronous reluctance motors.					
UNIT-V	Permanent Magnet Synchronous Motor (PMSM)	08 Hours				
Construction	n, Principle of Operation, EMF Equation, Torque Equation, Phasor Diagram, Circ	ele Diagram,				
Comparison	of Conventional and PMSM, Control of PMSM, Applications.					
UNIT-VI	Case Study	08 Hours				
Case studies	Case studies considering applications viz. electric vehicle					
- 11						
Reference Books						
1 Electri	1 Electric Machines D.P. Kothari, I.J. Nagrath Mc Graw Hill 4 <sup>th</sup> edition,2011					
Theory of Alternating Current Machines Alexander Langsdorf McGraw Hill 2 <sup>nd</sup> Edition,2000						

# F.Y. M.E. (Electric Vehicle Technology) Semester -III

[603503A]: Automotive Testing and Certification

Teaching Scheme:	Credit: 05	<b>Examination Scheme:</b>	
TH: 05Hours/Week		In Sem.Evaluation:50Marks	
		End Sem.Exam:50Marks	
		Total: 100 Marks	
Course Prerequisites:			
Course Objectives:			



1	1 Discuss working and operation of testing of EV. 2. 34.				
2	2 Discuss different methods of testing.				
3	Elabo	orate the schemes and regulations of testing.			
4	4 Discuss working and operation of testing of charging stations				
	•				
		Course Contents			
UNI	T-I	Basic of types of EV and Testing	08Hours		
Spec	cification	n& Classification of Vehicles (including M, N and O layout), Homologation &its Ty	pes.		
UNI	T-II	Schemes and Regulations	08Hours		
Regi	ulations	overview (EEC, ECE, FMVSS, AIS, CMVR), Type approval Scheme, homologation	for export,		
Con	formity	of Production, various Parameters			
UNI	UNIT-III EV Testing-I		08Hours		
Instr	ruments	and Type sofestracks, Static testing of vehicles-CMVR physical verification, Tyre	Tread Depth		
Test					
UNI	T-IV	EV Testing-II	08Hours		
Elec	etric veh	icle-Safety Norms, Energy consumption and Power test,			
UNIT-V Testing of Stations 08Hot		08Hours			
Dyn	amics te	sting of vehicles, Vehicle component testing. Tests for HEV and charging stations.			
UNI	UNIT-VI 08Hou		08Hours		
Test	ts for HE	EV and charging stations.			
Ref	erence l	Books			
1	1 Clemens Guhmann, Simulation and Testing for Vehicle Technology, Springer International Publishing				
	AG				

# F.Y. M.E. (Electric Vehicle Technology) Semester -III

### [603503B]: Automotive Embedded Systems and Communication Protocol

Teaching Scheme:	Credit: 05	<b>Examination Scheme:</b>
TH: 05Hours/Week		In Sem.Evaluation:50Marks
		End Sem.Exam:50Marks
		Total: 100 Marks
Course Prerequisites: Microcontroller		



Cou	rse Obj	ectives:	
1	To st	udy the automotive embedded system overview	
2	To understand the automotive hardware module		
3	To st	udy automotive software and its communication.	
		Course Contents	
UNI	T-I	AUTOMOTIVE EMBEDDED SYSTEM OVERVIEW	8Hours
Au	tomotiv	e Embedded System Technology, Overview of Embedded System Categories, V	arious
Em	bedded	Sub Systems like Chassis, Body, Driveline, Engine, Fuel, Emission, Brakes, Su	spension,
Emi	ssion, B	rakes, Suspension, Doors, Safety& Security, Comfort & Multimedia, Communic	cation &
Ligh	nting and	d Future Trends in Automotive Embedded Systems by Wire technologies.	
UNI	T-II	AUTOMOTIVE HARDWARE MODULE	8Hours
Cond	cept to	Market: Understanding Automotive Product Design Cycle, Microcontroller, ar	chitecture,
Men	nory ma	ap, I/O map, Building Blocks of Automotive Electronic Product: Actuators	, Sensors,
Sem	iconduc	tor Components, Devices, Integrated Circuits (ICs), Relay, Stepper motor, PCE	setc.
UNI	T-III	AUTOMOTIVE SENSORS	8Hours
Auto	omotive	Sensors and Transducers: Temperature, Force, Oxygen Sensor, LAMBDA Sensor	r,
Prox	kimity D	Distance Sensors, Speed, Engine Knock Sensor, Resistive Potentiometer & Flo	ow. Typical
Sens	sors Spe	cifications & Microcontroller Interfacing, Signal Processing circuit, Sensor Cali	bration.
UNI	T-IV	AUTOMOTIVE SOFTWARE	9Hours
C ·			anours
Stru	cture of	Tembedded program, infinite loop, and compiling, linking and locating, downloading	I.
			pading and
debu	ugging,	embedded program, infinite loop, and compiling, linking and locating, download	oading and N. Coding
debu	ugging, ndards a	embedded program, infinite loop, and compiling, linking and locating, downloantra processor Communication Protocols: I2C&I2S, SPI & USB, LIN and CA	oading and N. Coding
debu Stan	ugging, ndards ar T <b>-V</b>	Tembedded program, infinite loop, and compiling, linking and locating, download Intra processor Communication Protocols: I2C&I2S, SPI & USB, LIN and CA and Guidelines: MISHRAC &Automotive Operating System: OSEK/VDX, AUTO	oading and N. Coding OSAR.  9Hours
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Stan UNI The like Cert	ugging, ndards and T-V Validati Function ration Te	Tembedded program, infinite loop, and compiling, linking and locating, download Intra processor Communication Protocols: I2C&I2S, SPI & USB, LIN and CAIN Guidelines: MISHRAC &Automotive Operating System: OSEK/VDX, AUTO VERIFICATION & VALIDATION  Ion and Verification Process, Introduction to NI Lab VIEW for Automotive, Test nal Test, Black Box Test, Boundary level Test & Test Case Development, Relians Tests: EMI / EMC Tests as per AIS 004 standard, Environmental Test,	oading and N. Coding OSAR.  9Hours  Categories ability and
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# F.Y. M.E. (Electric Vehicle Technology) Semester -III

[603503C]: Modeling and Simulation of EVs

Teaching Scheme:	Credit: 05	<b>Examination Scheme:</b>
TH: 05Hours/Week		In Sem.Evaluation:50Marks



				End Sem.Exam:50Marks Total: 100 Marks	
Course Prerequisites: Matlab, Electrical Machines, Electric Vehicle mobility					
		ectives:	•	•	
1	Elabo	orate basic concepts of mod	leling of electrical mad	chines and discuss reference fra	me theory.
2	Deriv	e the DC machine model u	inder transient and ste	ady state conditions.	
3	Obta	n the dynamic model of 3p	hase induction machi	nes using reference frame theor	ry.
4	3 pha	se transformer.		model & analyze the per unit	model of the
5	Illust	rate the synchronous machi	ine modeling and obta	nin its per unit equivalent.	
			Course Content		
UNI			asic Concepts of Mo		8Hours
				nine representation of commutation	
		= -		ut damper bar and 3-phase is	nduction
		on's primitive machine-vo		•	T
UNI			Reference Frame Th		8Hours
		ime model of a two-phase to two phase transformation		ansformation to obtain constan  DC Machine Modeling	t matrices,
UNI		<u> </u>	DC Machine Model		8Hours
		cal model of separately exc		state and transient state analys	
appli	cation	of inertia load, transfer fun	action of separately ex	cited DC motor, mathematical	
		s, shunt motor, linearization			
UNI			eling of Three Phase		8Hours
			-	e, derivation of commonly used	
				ce frames model, synchronous	ly rotating
		mes model, equations in f			T
UNI			Transformer Model	0	8Hours
nor	mal sys	tems, per unit normalizatio	on, per unit three phase	ansformer connections, per phase quantities, change of base, per ge and phase angle control.	•
	<u>ysis 01</u> <b>T-VI</b>	iormai system, regulating t	Concepts in Simula	<u> </u>	8Hours
Intro Quei	duction		ontinuous System Stal description of GPS	imulation-Introduction Probab SS and Modeling principles a	ility Theory
Refe	rence l	Books			
1	R. Krishnan, "Electric Motor Drives-Modeling, Analysis Control", PHI LearningPrivateLtd,2009.				
2	P.C. Krause, Oleg Wasynczuk, Scott D. Sudhoff," Analysis of Electrical Machinery and Drive				
	Systems", 2ndEdition, Wiley(India),2010.				
3	Arthu	R Bergen and Vijay Vittal	," Power System Ana	lysis", 2 <sup>nd</sup> Edition,Pearson,2009	).
4	Chee-Mun Ong, "Dynamic Simulation of Electric Machinery using Matlab /Simulink", Prentice Hall,1998.				
5	11411,1	. , , , , , , , , , , , , , , , , , , ,			
J					



F.Y. M.E. (Electric Vehicle Technology)
Semester -III
[603504]: Seminar-II



Teaching Scheme:	Credit: 04	<b>Examination Scheme:</b>
TH: 04Hours/Week		TW:50 Marks
		OR/Presentation: 50 Marks
		Total: 100 Marks

Seminar II shall be on the topic relevant to latest trends in the field of concerned branch, preferably on the topic of specialization and based on broader area of interest to facilitate to proceed for dissertation work, selected by him/her approved by the guide and authority. He/she should study basic theory related to the topic from standard references. A student is expected to perform an exhaustive literature review of the topic. The student should focus on understanding the state of art – concept, literature published at standard platforms to enable the finalization of objective of his/her ME dissertation. A guide should maintain a weekly record of discussion related to the topic. The student shall submit the duly certified seminar report in standard format, for satisfactory completion of the work by the concerned Guide and head of the department/institute.



[603505]: Project Stage-I

Teaching Scheme:	Credit: 08	<b>Examination Scheme:</b>
08 Hours/Week		Term Work: 50 Marks
		Oral /Presentation: 50 Marks
		Total: 100 Marks

Project work Stage – I is an integral part of the project work. In this, the student shall complete the partial work of the project which will consist of problem statement, literature review, project overview, scheme of implementation (Mathematical Model/block diagram/ PERT chart, etc.) simulation model, Layout & Design of the Set-up and results if obtained. As a part of the progress report of Project Stage-I, the student shall deliver a presentation on the advancement in Technology pertaining to the selected dissertation topic. The project stage I is the progress presentation of dissertation work. The student should clearly present different stages in which dissertation work is to be completed, giving planning of the remaining part to be completed in Project Stage-II. Publication based on the work is desirable in the reputed national or international journal or in the proceedings of reputed and reviewed conferences. A guide should maintain record of discussion related to the topic; work carried out by the student. The student shall submit the duly certified progress report of Project work Stage-I in standard format for satisfactory completion of the work by the concerned guide and head of the Department / Institute.



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### **Semester -IV**

[603506]: Seminar-III

Teaching Scheme:	Credit: 05	<b>Examination Scheme:</b>
TH: 05 Hours/Week		Term Work: 50 Marks
		Oral Presentation: 50 Marks
		Total: 100 Marks

Seminar III shall preferably be an extension of seminar II. The content of report of seminar III will include development of the work till date along with relevant theory. A guide should maintain record of discussion related to the topic, work carried out by the student, action taken etc. The student shall submit the duly certified seminar report in standard format, for satisfactory completion of the work by the concerned guide and head of the Department/Institute.



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## S.Y. M.E. (Electric Vehicle Technology) Semester -IV

[603507]: Project Work Stage-II

Teaching Scheme:	Credit: 20	<b>Examination Scheme:</b>
TH: 20 Hours/Week		Term Work: 150 Marks
		Oral Presentation: 50 Marks
		Total: 200 Marks

In Project Work Stage – II, the student shall complete the remaining part of the project which will consist of simulation, fabrication of set up required for the project, workstation, conducting experiments and taking results, analysis & validation of results and conclusions. A student must publish a minimum of one paper based on the dissertation work in the reputed national or international journal or in the proceedings of reputed and reviewed conferences. Details of this publication should be mentioned in the final report. The dissertation work of candidate would be evaluated by the guide as well as panel of internal/external experts, before submitting it to the university to ensure basic minimum quality standard. A proper record of this evaluation needs to be maintained. A guide should maintain a record of discussion related to the topic, work carried out by the student, action taken etc. The student shall prepare the duly certified final report of project work in standard format for satisfactory completion of the work by the concerned guide, head of the Department and head of the Institute.