

Total No. of Questions : 5]

SEAT No. :

**P1701**

**[5131]-11**

[Total No. of Pages : 2

**M.Sc.**

**ELECTRONIC SCIENCE**

**EL1UT01 : Foundation of Semiconductor Devices**

**(2008 Pattern) (Semester - I)**

*Time : 3 Hours]*

*[Max. Marks : 80*

*Instructions to the candidates:*

- 1) *All questions are compulsory.*
- 2) *Figures to the right indicates Full marks.*
- 3) *Draw neat diagrams wherever necessary.*
- 4) *Use of non-programmable calculator is allowed.*

**Q1)** Attempt any two:

**[2 × 8 = 16]**

- a) Determine the time independent wave solution of a particle in infinite potential well.
- b) Explain formation of allowed and forbidden energy bands in solids using energy level diagram.
- c) Explain the operation of reverse biased P<sub>n</sub> junction. Obtain relation for junction capacitance.

**Q2)** Attempt any two:

**[2 × 8 = 16]**

- a) What are the advantages of equivalent electrical models of BJT for circuit analysis? Explain any one model in detail.
- b) How MESFET is different from JFET? Explain the basic operation of MESFET in detail.
- c) Draw the cross-sectional view of various MOSFET structures, explain small signal equivalent circuit of common source n-channel MOSFET.

**Q3)** Attempt any Four:

**[4 × 4 = 16]**

- a) Explain Heisenberg's uncertainty principle in short.
- b) What is meant by extrinsic semiconductor? Discuss with example.
- c) What is base width modulation in BJT?
- d) Write a short note on shattkey barrier diode.
- e) What are the frequency limitation factors on JFET.

**P.T.O.**

**Q4) Attempt any Four:**

**[4 × 4 = 16]**

- a) Define miller indices. Sketch the following atomic planes in simple cubic structure;

(1, 0, 0), (1, 1, 0), (1, 1, 1).

- b) Obtain an Einstein relation  $\frac{D_n}{\mu_n} = \frac{kT}{q}$ .

c) Write a short note on Light emitting diode.

d) Explain the operation of TRIAC and draw i-v characteristics.

e) Differentiate between JFET and MOSFET.

**Q5) Attempt any Four:**

**[4 × 4 =16]**

- a) Calculate deBroglie wavelength of an electron travelling at velocity of  $10^7$ cm/s.

b) How much percent of the permissible states at level  $E = E_F + 0.5\text{eV}$  is occupied if  $T = 0\text{K}$  and  $T = 100\text{K}$ ?

c) Explain working of tunnel diode.

d) What is meant by MOSFET Scaling?

e) What is cut-off frequency and beta cut-off frequency? What is the relation between two?



Total No. of Questions : 5]

SEAT No. :

**P1702**

**[5131]-12**

[Total No. of Pages : 3

**M.Sc.**

**ELECTRONIC SCIENCE**

**EL1UT - 02: Analog Circuit Design and Analysis  
(2008 Pattern) (Semester - I)**

*Time : 3 Hours]*

*[Max. Marks : 80*

*Instructions to the candidates:*

- 1) *All questions are compulsory.*
- 2) *Figures to the right indicate full marks.*
- 3) *Draw neat diagram wherever necessary.*
- 4) *Use of log-table /non-programmable calculator is allowed.*

**Q1)** Attempt any two.

- a) What do you mean by ideal current source? With neat diagram explain the working of widlar current source and wilson current source. **[8]**
- b) Obtain the inverse laplace transformation for the given functions: **[8]**

i) 
$$F(s) = \frac{5s + 4}{(s - 1)(s^2 + 2s + 5)}$$

ii) 
$$F(s) = \frac{s - 3}{s^2 + 4s + 13}$$

- c) What is two port network? Explain its impedance, hybrid and transmission parameters. **[8]**

**Q2)** Attempt any two.

- a) i) Obtain Laplace transform of following **[4]**
  - $\sin 3t$
  - $t^3$
- ii) Explain following terms associated with op-amp **[4]**
  - CMRR
  - Slew Rate

**P.T.O.**

- b) What is active Filter? State advantages of active filter over passive filter. Design second order highpass filter for a cut-off frequency of 1KHz and passband gain 4. [8]
- c) i) Explain need of high power op-amp. What are the relevant parameters of a power op-amp? [4]
- ii) Explain the working of charge redistribution ADC. [4]

**Q3)** Attempt any two.

- a) i) Explain the terms: Transfer function, pole and zero of a network. [4]
- ii) Explain working of weighted capacitor DAC. [4]
- b) i) Explain the causes of instability in op-amp circuits. What are internal and external frequency compensation techniques? [4]
- ii) What is the need for a sample and hold circuit? Define acquisition and aperture time. [4]
- c) i) Explain output stage of op-amp 741. [4]
- ii) What is the need for low power design? [4]

**Q4)** Attempt any two.

- a) i) Design a m-derived low pass filter having cut-off frequency of 1KHz, design impedance of  $400\Omega$  and the resonant frequency 1100 Hz. [4]
- ii) Explain series RLC circuit in brief. [4]
- b) i) Explain in brief the output current boosting techniques for general purpose op-amp with proper circuit diagram. [4]
- ii) Draw the circuit diagram of practical integrator circuit. Give designing steps of it. [4]
- c) i) Explain specification of DAC convertor. [4]
- ii) Explain micropower design techniques. [4]

**Q5)** Attempt any four.

- a) What is programmable op-amp? How its parameters can be programmed? **[4]**
- b) Explain R-2R Ladder type D/A conversion techniques. **[4]**
- c) State applications of ADC'S and DAC'S. **[4]**
- d) What is peak defector? Explain working of peak detector circuit using op-amp. **[4]**
- e) Explain the working of Half wave precision rectifier circuit. **[4]**



Total No. of Questions : 5]

SEAT No :

**P1703**

**[5131] - 13**

[Total No. of Pages :3

**M.Sc.**

**ELECTRONIC SCIENCE**

**ELIUT03:Instrumentation and Measurement Techniques  
( 2008 Pattern) (Semester - I)**

*Time : 3 Hours]*

*[Max. Marks : 80*

*Instructions to the candidates:*

- 1) *All questions are compulsory.*
- 2) *All questions carry equal marks.*
- 3) *Draw neat labeled diagrams wherever necessary.*
- 4) *Use of logarithmic table and non-programmable calculator is allowed.*

**Q1) a) Answer any two of the following: [2×6=12]**

- i) Draw the block diagram of generalized measurement system. Explain signal manipulation element of it.
- ii) Give detail classification of instruments with different methods of measurement.
- iii) List the factors influencing the choice of transducer for the measurement of physical parameter.

**b) Define the following: [4]**

- i) Sensitivity,
- ii) Accuracy,
- iii) Resolution and
- iv) Precision.

**Q2) a) Answer any two of the following: [2×6=12]**

- i) Describe Voltmeter and Ammeter loading effect with suitable example.
- ii) Give detail classification of transducers.
- iii) State the dynamic characteristics of measurement system. A first order system used to measure signal with frequency context upto 100Hz with amplitude accuracy of 5%. Calculate maximum time constant and phase shift at 50Hz.

**b) Give applications of LVDT. State advantages and disadvantages of LVDT.[4]**

**P.T.O.**

- Q3) a)** Answer any two of the following: **[2×6=12]**
- i) Describe working principle of capacitive, inductive and Resistive transducers with suitable example.
  - ii) Write different types of vacuum gages. Explain working principle of Kundsen gage.
  - iii) With neat block diagram explain working of general telemetry system. State the types of telemetry systems.
- b) State different methods of flow measurement. Explain the working principle of turbine flow meter. **[4]**

- Q4)** Answer any four of the following: **[4×4=16]**
- a) Draw the following OPAMP circuits and write their OIP equations.
    - i) Differentiator,
    - ii) Schmitt Trigger,
    - iii) Trans-conductance amplifier and
    - iv) Instrumentation amplifier with three OPAMP.
  - b) With circuit block diagram explain voltage and current telemetry systems.
  - c) Describe working principle of DVM. How different ranges incorporated in DVM.
  - d) Describe different techniques used for magnetic recording. State advantages of FM type magnetic recording.
  - e) Draw the block diagram of sound Level Meter. Explain how it is used for sound pressure level measurement.
  - f) List the different types of strain gages. Derive an expression for gage factor of simple wire type strain gage.

- Q5)** Answer any four of the following: **[4×4=16]**
- a) List the temperature transducers. Explain the working principle of resistive temperature transducers.
  - b) A  $10\text{K}\Omega$  variable resistor has a linearity of 0.1% and the movement of contact arm is  $320^\circ$ . Determine the maximum position deviation in degree and resistance deviation in Ohm. If the instrument is to be used as a potentiometer with a linear scale of 0 to 1.6V. Determine the maximum voltage error.

- c) A compressive force is applied to a structural member. The strain is 5 microstrain. Two separate strain gages are attached to the structural member, one is nickel wire having gage factor of - 12.1 and other is nichrome wire with gage factor of 2. Calculate the value of resistance of the gages after they are strained. The unstrained resistance of the gages is  $120\ \Omega$ .
- d) A thermistor has a resistance of  $3980\ \Omega$  at the ice point, and  $794\ \Omega$  at  $50^\circ\text{C}$ . The resistance temperature relation is  $R_T = aR_0 e^{(b/T)}$ . Calculate the constant  $a$  and  $b$ . Also calculate the range of resistance to be measured in case of the temperature varies from  $40^\circ\text{C}$  to  $100^\circ\text{C}$ .
- e) A simple equal arm voltage sensitive bridge is initially balanced. Three arms consist of ordinary resistors and fourth one is thermistor. Each arm has nominal resistance of  $10\text{K}\ \Omega$ . The bridge is excited with  $\sigma\text{V}$  dc source. If the temperature change causes a +5% change in thermistor resistance. What output voltage of the bridge? If a -5% change in resistance is caused. What will be the bridge output.
- f) A voltmeter is used to measure the voltage of a circuit. Having an output resistance of  $1\text{K}\ \Omega$  and the open circuit voltage is 6V at its 10V scale. Find the error in the measurement.





Total No. of Questions : 5]

SEAT No. :

**P1704**

**[5131]-21**

[Total No. of Pages : 2

**M.Sc.**

**ELECTRONIC SCIENCE**

**EL2-UT 04 : Applied Electromagnetics, RF and Microwave  
(2008 Pattern) (Semester - II)**

*Time :3 Hours]*

*[Max. Marks : 80*

*Instructions to the candidates:*

- 1) *All the question are Compulsory.*
- 2) *Figures to the right indicate full marks.*
- 3) *Draw neat diagrams wherever necessary.*
- 4) *Use of log tables / non-programmable calculators is allowed.*

**Q1)** Attempt any two of the following:

**[2 × 8 = 16]**

- a) What are retarded potentials? Obtain the expressions for retarded potentials.
- b) From Maxwell's equations, obtain wave equations in free space.
- c) What is Gunn effect? Draw the schematic diagram of an n-type GaAs diode. What are the modes of operation of a Gunn diode?

**Q2)** Attempt any two of the following:

**[2 × 8 = 16]**

- a) From the first principles, obtain the expression for power radiated by a half - wave dipole.
- b) What is a Smithchart? What are its uses? State its important characteristics.
- c) Compare MESFET & MOSFET with reference to the structure, operating principles and applications.

**Q3)** Attempt any four of the following:

**[4 × 4 = 16]**

- a) With suitable examples, explain the electromagnetic effects in high speed digital systems.
- b) With the help of a neat diagram explain the working of a magnetron.

***P.T.O.***

- c) What are the different types of losses in microstriplines?
- d) What is a cavity resonator? What is its use?
- e) State Poynting theorem & explain the terms in its equation.

**.Q4)** Attempt any four of the following:

**[4 × 4 = 16]**

- a) Define the following terms for an antenna:
  - i) Gain
  - ii) Directivity
  - iii) Aperture.
- b) Write a short note on global positioning (GPS).
- c) Write a short note on EMI. How can it be controlled?
- d) Write a short note on optical waveguides.
- e) How are antennas classified based on their structure?

**Q5)** Attempt any four of the following :

**[4 × 4 = 16]**

- a) A transmission line has the following parameters:  $R= 1\Omega/m$ ,  $G=1 \text{ m mho/m}$ ,  $f = 1 \text{ GHZ}$  ,  $L = 10 \text{ nH/m}$   $C=0.2 \text{ PF/m}$ . Calculate the characteristic impedance.
- b) A coplanar stripline carries a power of 300mW & peak current of 150mA. Determine the characteristic impedance of coplanar stripline.
- c) A rectangular waveguide has dimensions of 8 cm × 4 cm and operates in  $TE_{10}$  mode. Find the cut-off frequency.
- d) A loss-less line has characteristic impedance of  $40\Omega$  and has terminal impedance of  $80\Omega$ . The line is energised by a generator with output impedance of  $50\Omega$  and open circuit voltage of 30V(rms). Find the input impedance and reflection coefficient.
- e) A transmission line has characteristic impedance of  $60 + j0.35\Omega$  and it is terminated in load impedance of  $75 - j50\Omega$ . Find the SWR.



Total No. of Questions : 5]

SEAT No. :

**P1705**

**[5131]-22**

[Total No. of Pages : 2

**M.Sc.**

**ELECTRONIC SCIENCE**

**EL2UT05 : Communication Electronics**

**( 2008 Pattern) (Semester - II)**

*Time : 3 Hours]*

*[Max. Marks : 80*

*Instructions to the candidates:*

- 1) *All questions are compulsory.*
- 2) *Figures to the right indicate full marks.*
- 3) *Draw neat diagrams wherever necessary.*

**Q1)** Attempt any FOUR of the following:

**[4×4=16]**

- a) Describe any two applications of ISDN in short.
- b) With reference to satellite communication, explain the terms uplink and cross link.
- c) With the help of neat diagram, explain the working of base neutralisation.
- d) Explain the working of very small aperture (VSAT) in short.
- e) With the help of circuit diagram, explain the working of diode detector.
- f) Describe any two signal encoding format in short.

**Q2)** Answer any TWO of the following.

**[2×8=16]**

- a) Draw the circuit diagram of RF tuned amplifier, write its working. Write the advantages and disadvantages of it.
- b) What is quadrature amplitude modulation (QAM)? With the help of diagram, explain the working of QAM (8 or 16).
- c) Draw the block diagram of super heterodyne receiver. Explain the working of each block in short.

**P.T.O.**

**Q3)** Write any FOUR of the following. **[4×4=16]**

- a) With the help of diagram, explain the working of transponder.
- b) Describe digital subscriber line (DSL) in short.
- c) Draw the frame structure of SDLC. Explain the function of each field in short.
- d) With the help of block diagram, explain the working of single side band (SSB).
- e) Explain the working of automatic gain control circuit.
- f) Describe the working of dialing system of telephone system.

**Q4)** Answer any TWO of the following. **[2×8=16]**

- a) Draw the frame structure of XMODEM. Explain the function of each field of it. Write the importance of it.
- b) With reference to pulse code modulation, explain the terms
  - i) Sample and hold.
  - ii) Quantisation.
  - iii) Quantisation noise.
  - iv) Encoding.
- c) What is frequency division multiplexing (FDM)? Draw the block diagram of FDM. Describe its working. Write its advantages over TDM.

**Q5)** Attempt any FOUR of the following. **[4×4=16]**

- a) Describe any two applications of geostationary satellite.
- b) For AM, prove that the power contained in the side bands is one third of the total power.
- c) With the help of block diagram, explain the working of phase shift keying (PSK) modulator.
- d) Describe the equipment and atmospheric noise in short.
- e) Describe any one data compression technique in detail. Write the advantages of it in communication.

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Total No. of Questions : 5]

SEAT No. :

**P1706**

**[5131]-23**

[Total No. of Pages : 2

**M.Sc.- I**

**ELECTRONIC SCIENCE**

**EL2UT06:Digital System Design using VHDL  
(2008 Pattern) (Semester - II)**

*Time : 3 Hours]*

*[Max. Marks : 80*

*Instructions to the candidates:*

- 1) *All questions are compulsory.*
- 2) *Figures to the right indicate full marks.*
- 3) *Neat diagrams must be drawn wherever necessary.*

**Q1)** Attempt any two of the following:

- a) What is entity in VHDL program. Explain process statement in VHDL and write a VHDL code for 4:1 multiplexer using process statement. [8]
- b) Write short note on package and library with respect to their declaration, definition, syntax & example. [8]
- c) What are variables, signals and constants in VHDL? Explain userdefined and predefined VHDL types for them. [8]

**Q2)** Attempt any two of the following :

- a) Explain with circuit diagram a keyboard encoder, the key should be displayed till the next key is not pressed. [8]
- b) Give the design of logic circuit of the processor unit. How will you combine logic arithmetic circuits to form ALU? Illustrate with block diagram. [8]
- c) i) Implement the following using PLA  
 $F1 = \sum m(1,2,4,7,8,11,12,13)$   
 $F2 = \sum m(2,3,9,11)$   
 $F3 = \sum m(10,12,13,14)$   
 $F4 = \sum m(2,4,8)$  [4]
- ii) Simplify  $f(A,B,C,D) = \sum(1,2,3,5,7,11,13)$  using K-map. [4]

**P.T.O.**

**Q3)** Attempt any two of the following:

- a) Design 3 bit synchronous up counter using T-flipflops. [8]
- b) i) Explain the following in brief. [4]
  - 1) Excitation table
  - 2) State table
  - 3) State diagram
  - 4) Ripple counter.
- ii) Draw the state diagram for D, J-K, T, R-S flipflops. [4]
- c) With proper state table and state diagram, write a VHDL code for traffic light controller using finite state machine(FSM). [8]

**Q4)** Attempt any two of the following:

- a) i) Compare a D flipflop and a latch. Illustrate your answer with proper timing diagram. [4]
- ii) State the difference between static and dynamic RAM. Explain how data is written in SRAM. [4]
- b) i) Define scratch pad memory. How is it different from main memory. [4]
- ii) Write a VHDL code for 2:4 decoder. [4]
- c) i) Write the difference between PLA & PAL. [4]
- ii) What is GAL? Implement  $AC + B\bar{C} + \bar{A}BC$  using GAL 16V8 in simple mode. [4]

**Q5)** Attempt any two of the following:

- a) Draw and explain FPGA architecture in short. [8]
- b) i) Design a 4-bit binary to gray converter using K-map. [4]
- ii) Write a VHDL code for 4 bit binary to gray converter. [4]
- c) What do you mean by synchronous counter. Write a VHDL code for 4 bit synchronous up counter. [8]



Total No. of Questions : 5]

SEAT No. :

**P1707**

**[5131]-31**

[Total No. of Pages : 2

**M.Sc. - II**

**ELECTRONIC SCIENCE**

**EL3 UT05 : Embedded Systems  
(2008 Pattern) (Semester - III)**

*Time : 3 Hours]*

*[Max. Marks : 80*

*Instructions to the candidates:*

- 1) *All questions are compulsory.*
- 2) *Figures to the right indicate Full marks.*
- 3) *Draw neat diagrams wherever necessary.*

**Q1)** Attempt any FOUR of the following:

**[4 × 4 = 16]**

- a) Draw an interface of DC motor and a switch to 8051. Write an assembly/ 'C' program to rotate DC motor clockwise, if switch is closed, rotate it anticlockwise if switch is open.
- b) What is an embedded system? Write differences between Microprocessor and microcontroller.
- c) Explain the following:
  - i) Compiler
  - ii) Simulator
- d) Explain status register of PIC Microcontroller.
- e) Explain serial communication in 8051. Draw data frame used in asynchronous communication.

**Q2)** Attempt any FOUR of the following:

**[4 × 4 = 16]**

- a) Explain interrupts of 8051.
- b) Explain input output ports of 8051.
- c) Describe watch dog timer.
- d) Explain data and program memory organization of PIC Microcontroller.
- e) Explain with example addressing modes of AVR microcontroller.

**P.T.O.**

**Q3) Attempt any TWO of the following: [2 × 8 = 16]**

- a) Draw programming Model of 8051 and explain it in short.
- b) Draw an interfacing of stepper motor to 8051. Write an assembly / 'C' program to rotate stepper motor clockwise continuously.
- c) Draw and explain architecture of AVR Microcontroller.

**Q4) Attempt any FOUR of the following: [4 × 4 = 16]**

- a) Write any four features of PIC 16F 877 microcontroller.
- b) Explain hardware development tools.
- c) Explain methods of time delay generation in embedded C for 8051.
- d) Write an assembly /'C' program to transmit "YES" string to computer with band rate 9600, one start bit and one stop bit. (For 8051).
- e) Explain different methods used to download HEX File in flash memory of Microcontroller.

**Q5) Attempt any TWO of the following: [2 × 8 =16]**

- a) Explain harvard and Van-neuman architecture. Compare RISC and CISC processors.
- b) Write an assembly / 'C' program for AVR microcontroller to display "ELECTRONICS" on First line of LCD.
- c) Explain steps used in generation of PWM output using CCP module of PIC Microcontroller. Find values of registers PR2, CCP1RL, DCIB2 : DCIB1 to generate PWM of 1kHz with 75% duty cycle using CCP module. Use XTAL = 10 MHz.





Total No. of Questions : 5]

SEAT No. :

**P1708**

[5131]-41

[Total No. of Pages : 2

M.Sc.

**ELECTRONIC SCIENCE**

**EL4UT - 06 : Control Systems: Theory and Applications  
(2008 Pattern) (Semester - IV)**

*Time :3 Hours]*

*[Max. Marks : 80*

*Instructions to the candidates:*

- 1) *All questions are Compulsory.*
- 2) *Figures to the right indicate full marks.*
- 3) *Use of non-programmable calculator is allowed.*

**Q1) Solve any Two:**

**[2 × 8 = 16]**

- a) Explain Zeigler - Nichols method for process loop tuning.
- b) Discuss SCADA system in detail. What are its advantages. Give its applications
- c) Explain any three data handling instructions for PLC.

**Q2) Solve any Two:**

**[2 × 8 = 16]**

- a) Discuss closed loop transient response of control systems on the basis of location of its closed loop poles.
- b) What is Proportional control mode? How offset error in P-mode can be reduced? How it can be implemented using opamp.
- c) With the help of suitable diagrams and equations, explain any four rules or techniques of block diagram reduction.

**Q3) Solve any four:**

**[4 × 4 = 16]**

- a) Examine the stability of control system having characteristics equation:

$$s^8+5s^6+2s^4+3s^2+1=0$$

using Routh's Method.

**P.T.O.**

- b) Define transfer function. obtain a transfer function for passive RC integrator circuit.
- c) Explain three position controller action with the help of appropriate diagram
- d) Explain angle and magnitude condition for a point to be on root locus.
- e) List the major differences between a modular PLC and a fixed PLC.

**.Q4) Solve any four:**

**[4 × 4 = 16]**

- a) What is meant by single variable and multivariable alarms.
- b) Design a PI controller with proportional band 30% and integral gain 0.1%(%-s). The 4 to 20 mA input converts 0.4 to 2.0v signal and output to be 0 to 10v.
- c) Explain Nyquist stability criterion for stability of control system.
- d) What is PLC networking. Explain in brief.
- e) Develop a ladder diagram for coffee vending machine.

**Q5) Solve any Four:**

**[4 × 4 = 16]**

- a) Compare open loop system with closed loop system with suitable example.
- b) Define the terms; integral wind up and derivative over run.
- c) Write a short note on soft PLC.
- d) What is the need of feedback, feed forward and adaptive control in process control
- e) Inverse Laplace transform of a system in time domain is  $e^{-5t}$ , It's input is  $i(t) = 2$ . Determine its output  $c(t)$ .

